

# Extraction of Fundamental Components from Distorted Spectral Measurements

Mr. Caleb Rascon

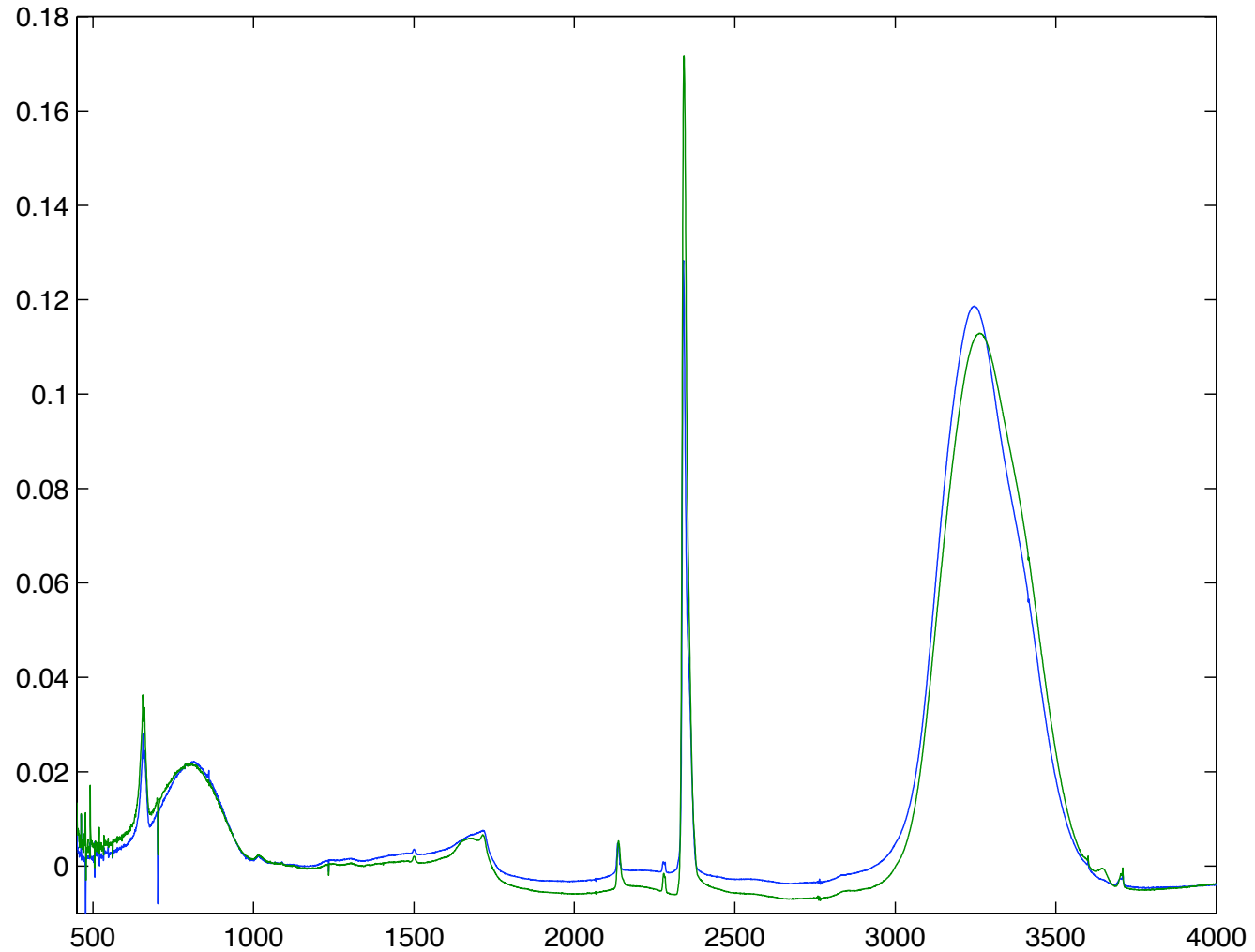
Prof. Barry Lennox

Dr. Ognjen Marjanovic

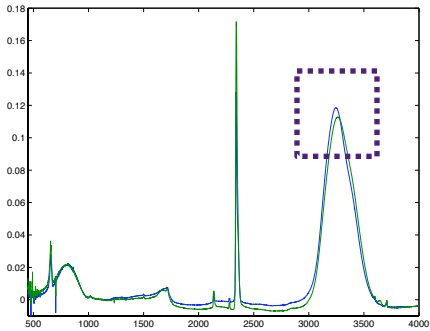
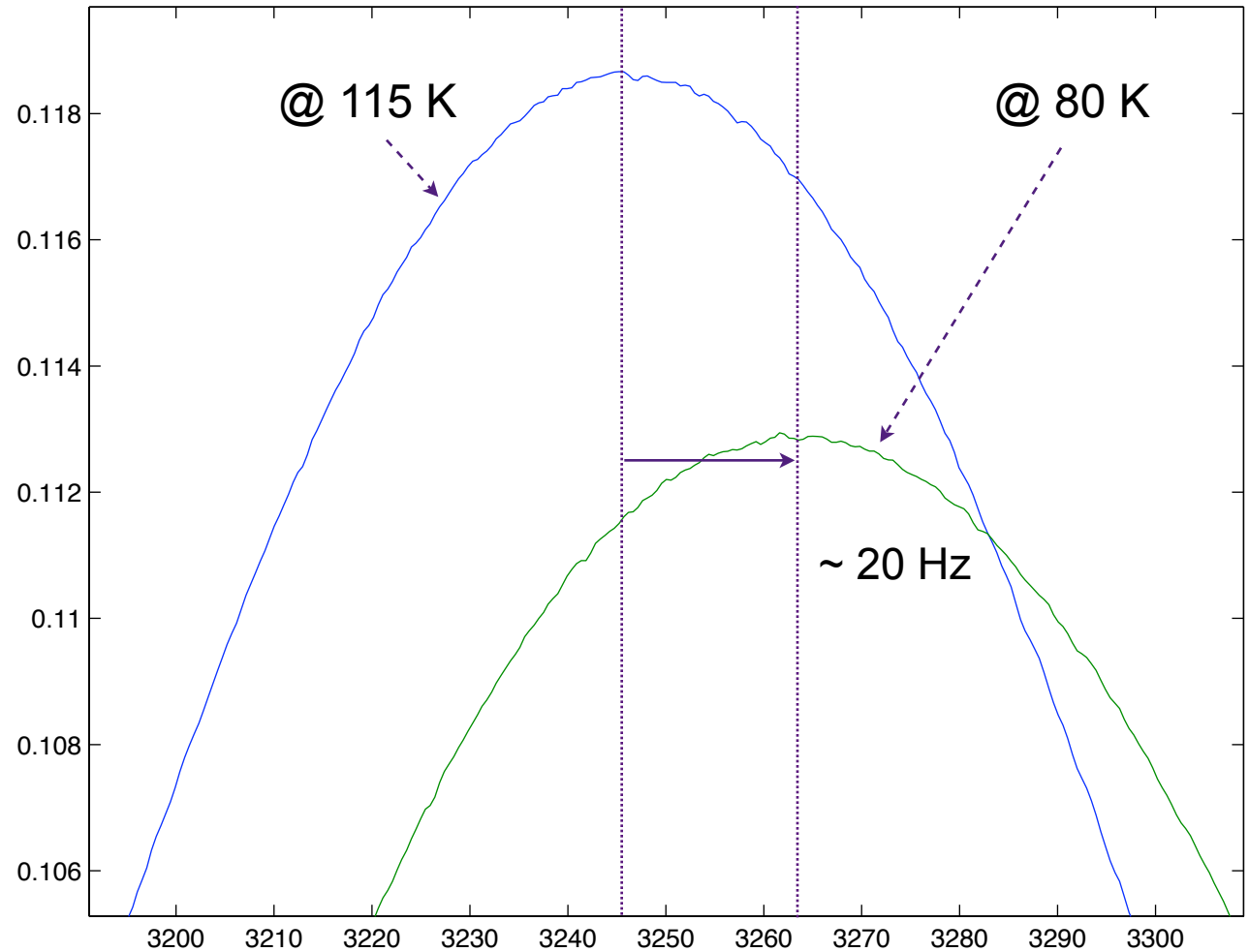
# Using Spectral Data in Monitoring

- Crystallisation of active ingredients (Yu et al, 2003)
- Identify material concentrations (Dyrbe et al, 2002)
- Component identification
  - Self-Modelling Curve Resolution Methods
    - Alternating Least Squares
    - SIMPLISMA
  - Blind Source Separation
    - Principal and Independent Component Analysis
- Viable as observed variables in feedback control
  - Or are they?

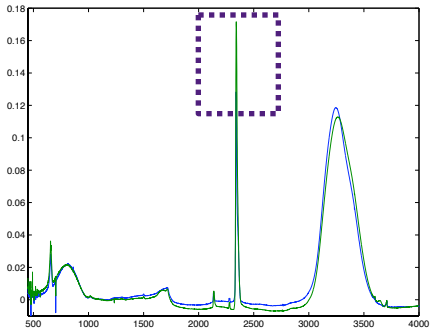
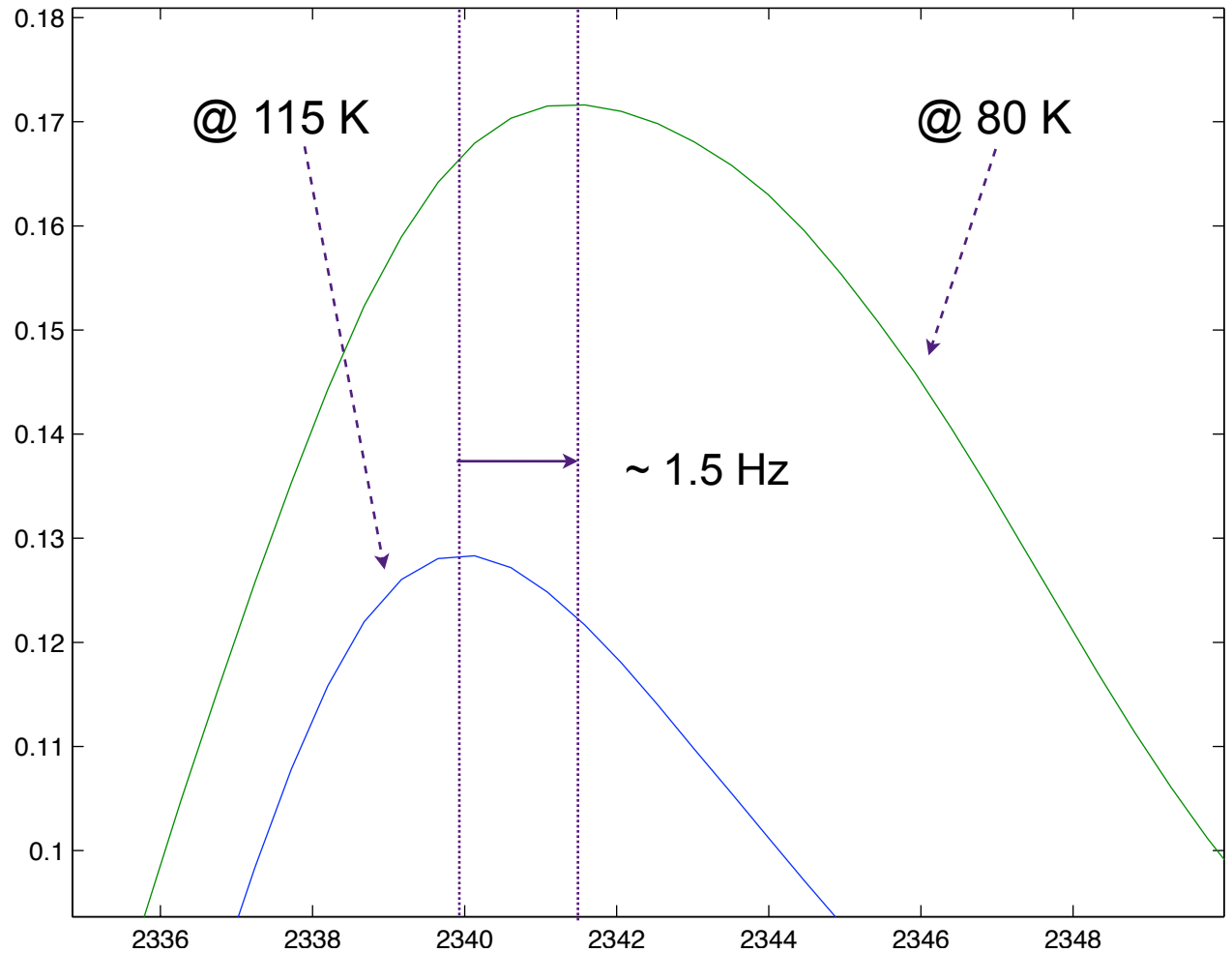
# Spectral Distortion (Ice Analogs)



# First Component



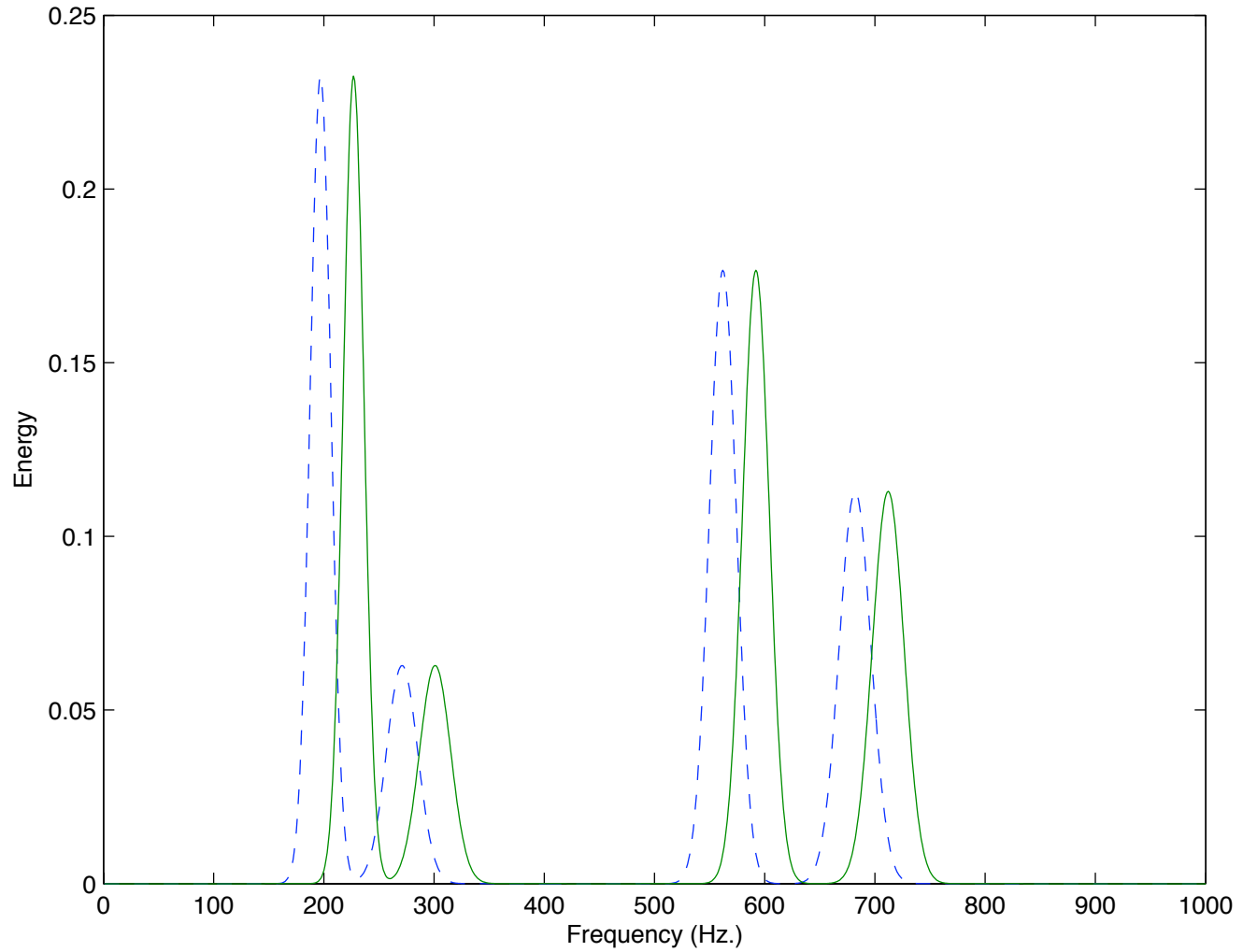
# Second Component



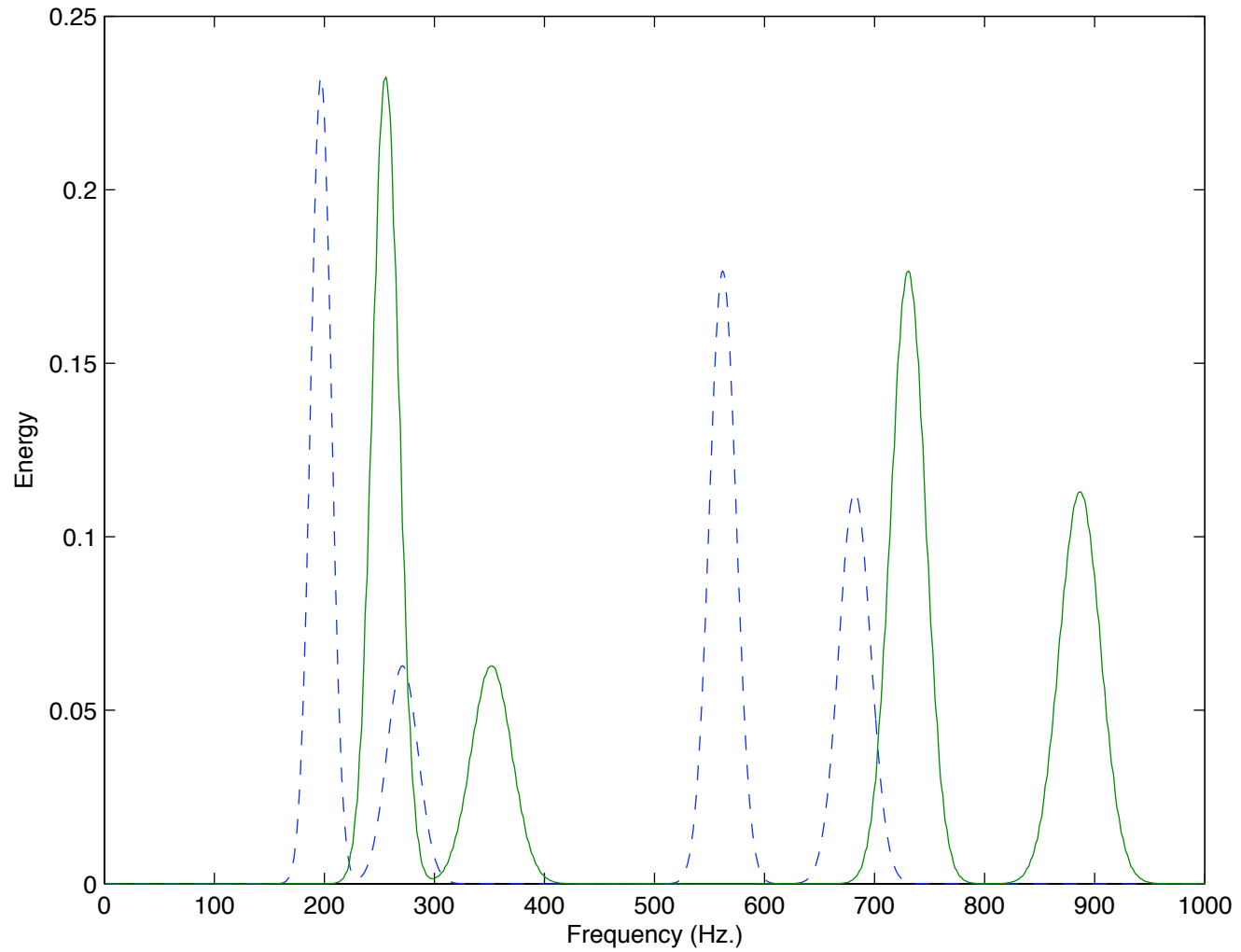
# Sources of Spectral Distortion

- Temperature changes
- Pressure changes
- Sensor de-calibration
- Foreign components (even external light sources)
  
- Baggerly et al. (2004) have observed spectral distortion from one instrument to another within the same laboratory.
  
- Most observed:
  - Shift**, aka *Frequency Displacement*, reported to be caused by changes in pressure, temperature, or a foreign component.
  - Warp**, aka *Frequency “Stretching”* or *“Shrinking”*, reported also to be caused by a change in temperature.

# Shift

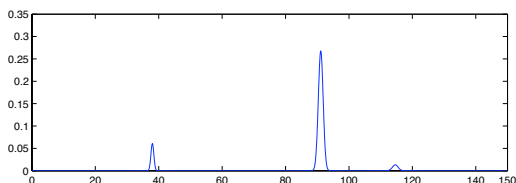
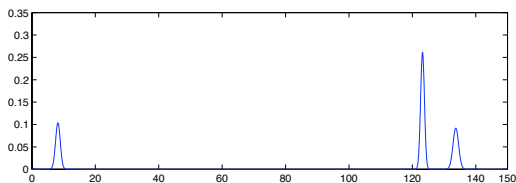


# Warp





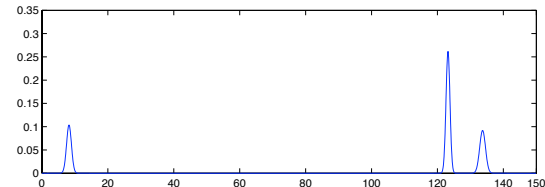
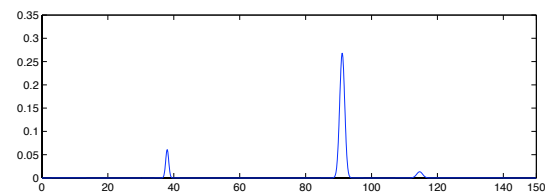
# Effects on Component Identification Methods



Sources

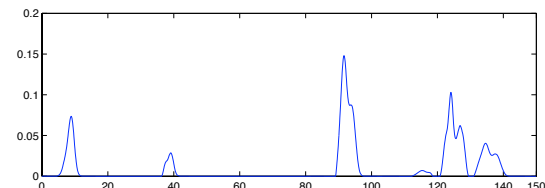
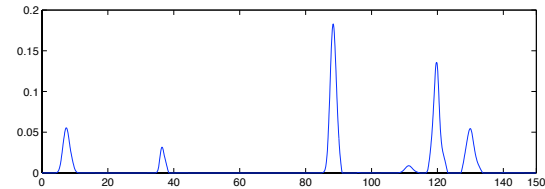
Data set without shift nor warp

ALS



Data set with shifts between [-2 2] Hz and warps between [-5 5] %

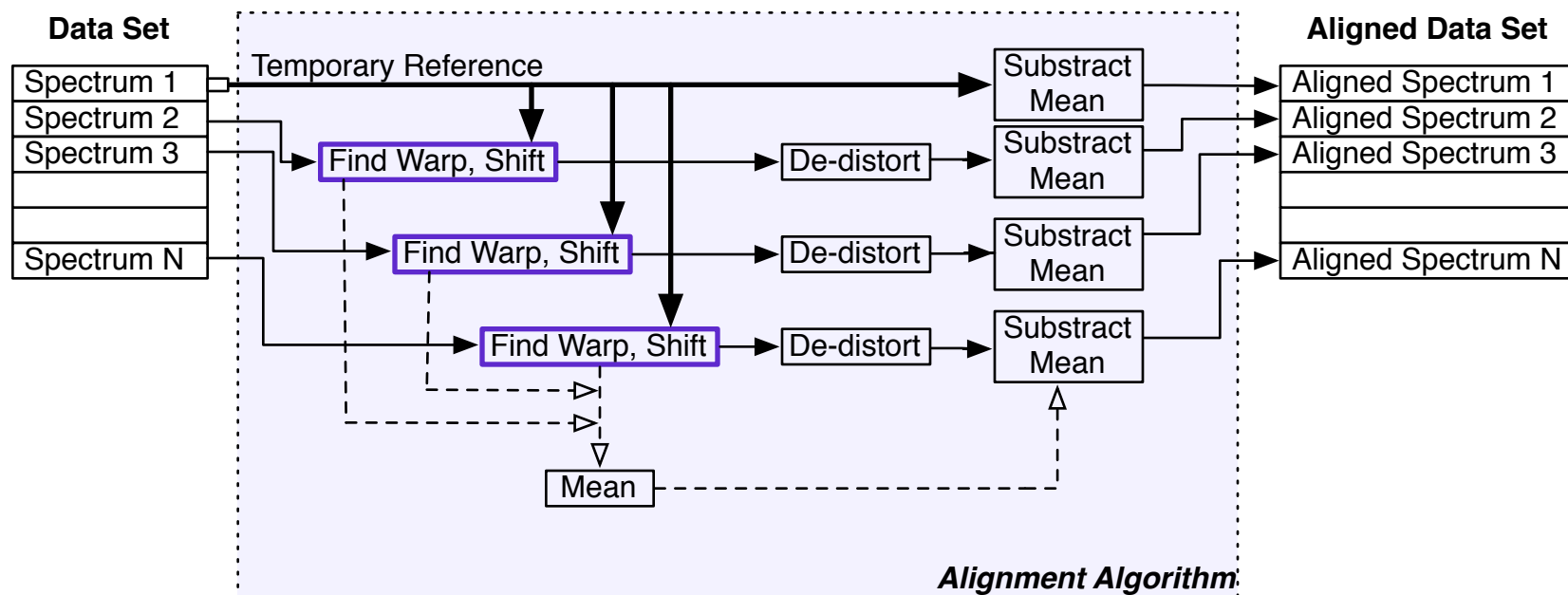
ALS



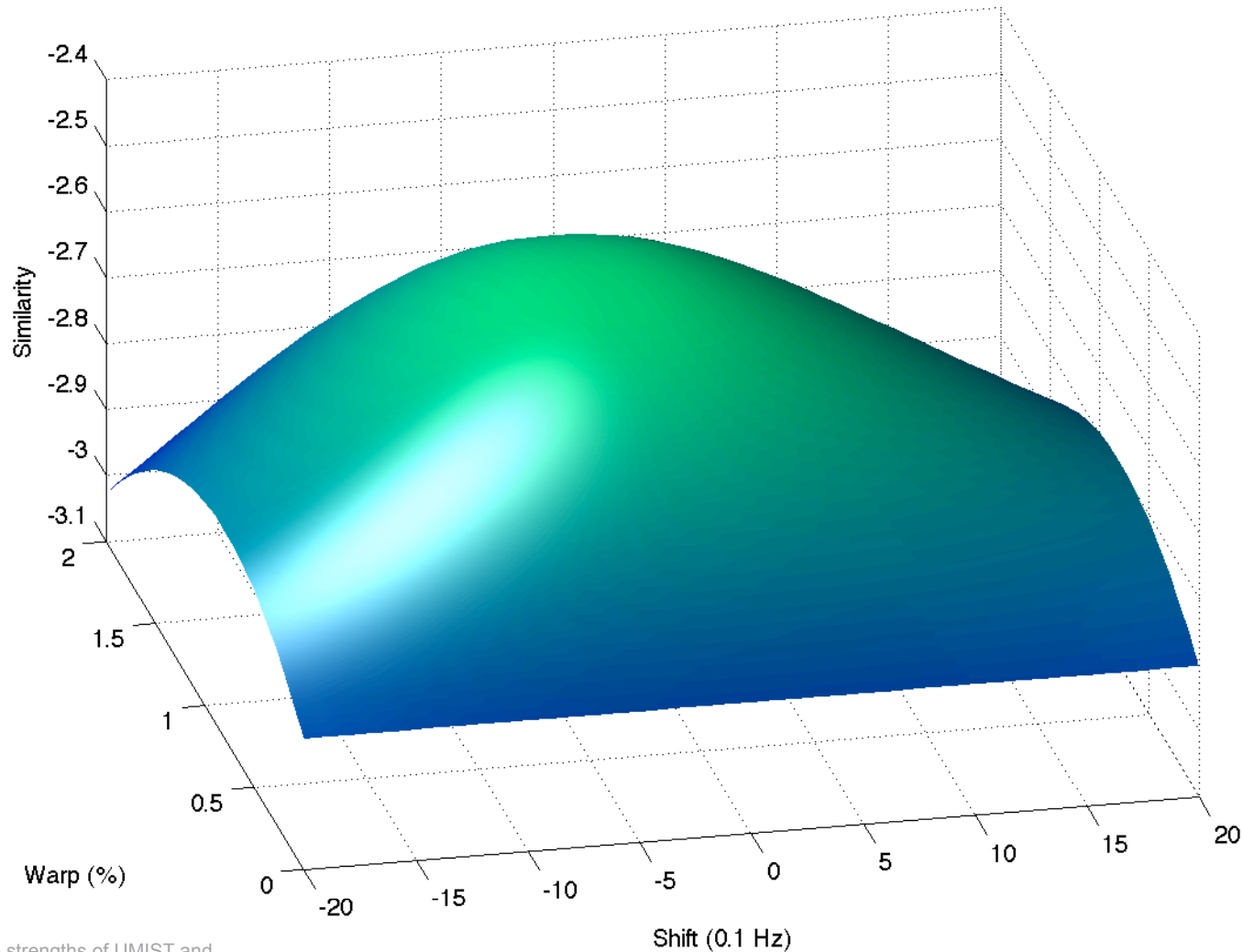
# Alignment as an Optimisation Problem

- Components inside a set of spectra need to be aligned to be properly identified.
  - However, the ‘reference’ frequency location is irrelevant in the identification process.
- The spectra can be aligned using any one of the signals as a temporary reference.
- An optimisation algorithm is applied to find the optimal amounts of counter-distortion (de-shift, de-warp, etc.) for each spectrum, to be the most similar to the temporary reference.
- Using information gathered for each aligned spectrum, a mean tendency for each type of distortion is calculated, and assumed as the amount of distortion suffered in the temporary reference.

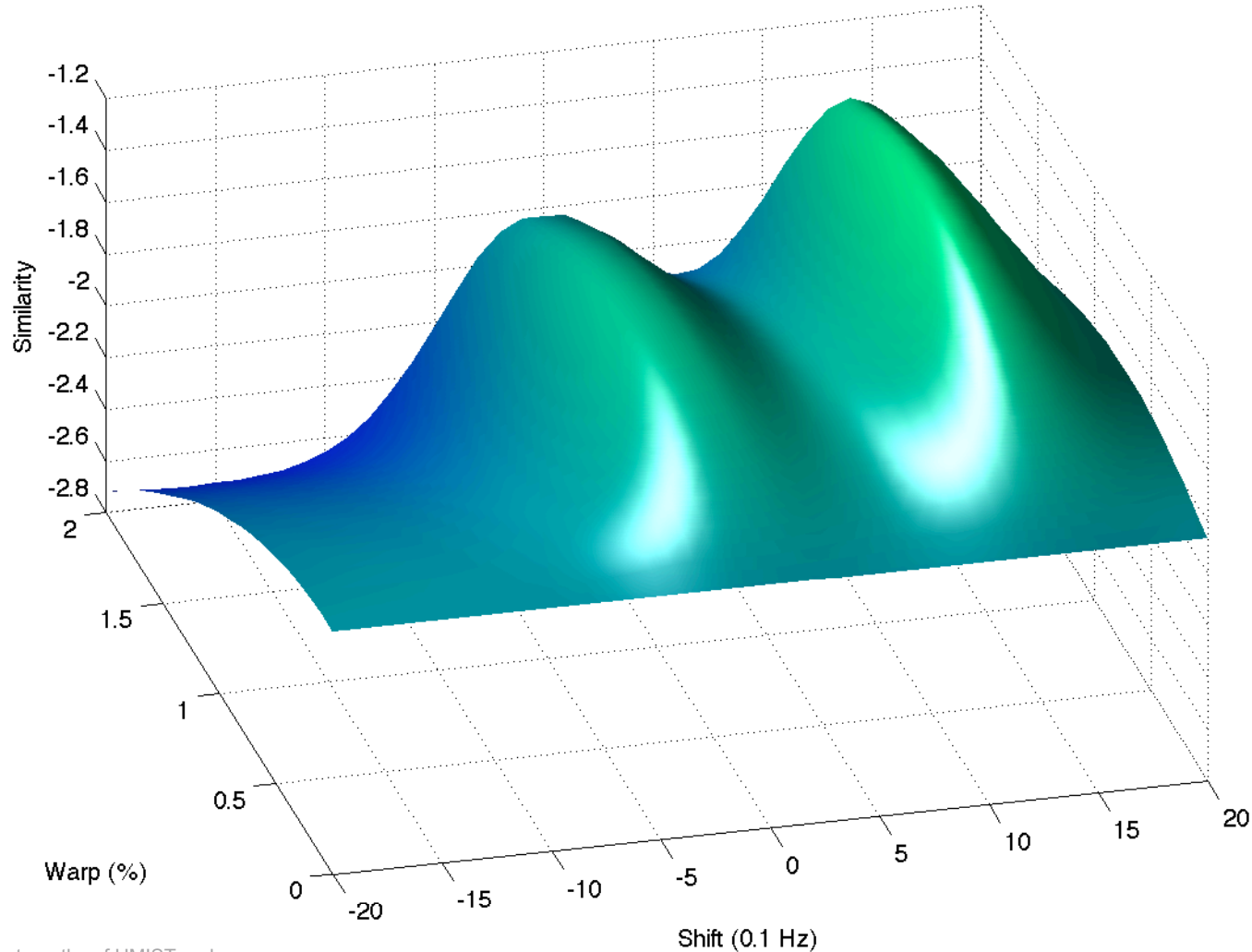
# Algorithm Summary



# Example of Solution Space Observed



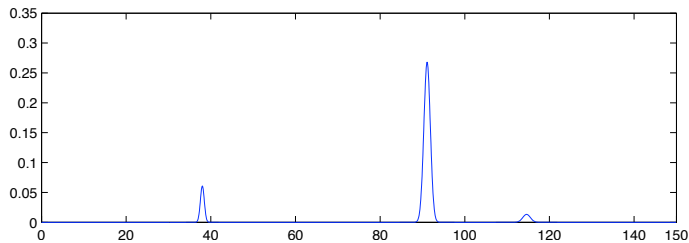
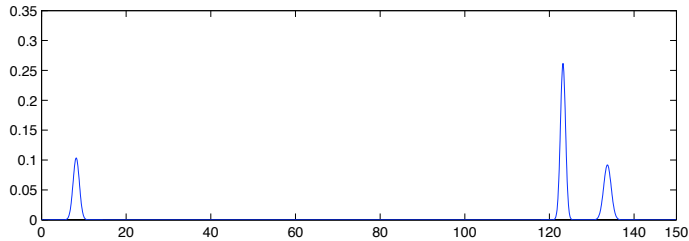
# Another Example of Solution Space



# Optimisation Algorithm

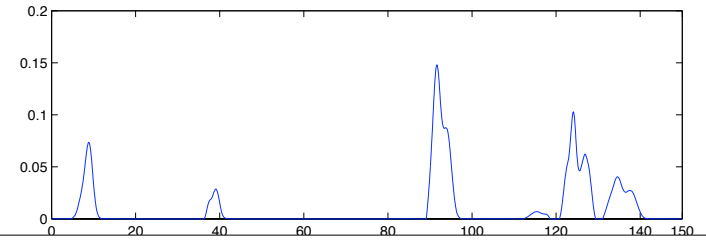
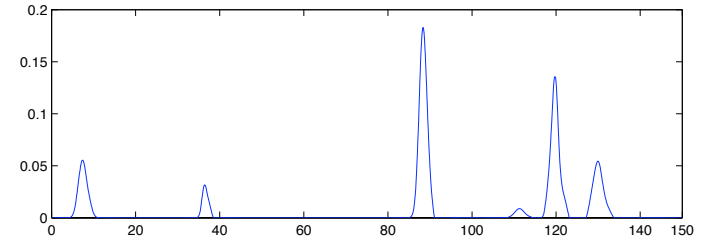
- The unpredictable nature of the problem makes it necessary to apply a black-box oriented optimisation algorithm.
- **Particle Swarm Optimisation:**
  - Simulates a flock of bird ‘flying’ in the solution space.
  - Relatively easy to implement and visualise.
  - Proven to converge under specific tuning parameters (Clerc et al., 2002).
  - As good or better results than Genetic Algorithms (Kennedy et al., 1995).
- Given the definition of the problem, other algorithms can be applied.

# Results of Pre-Aligning before ALS

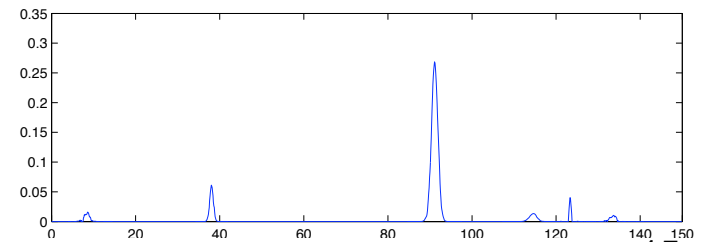
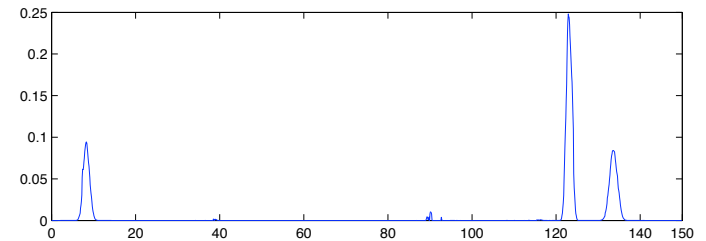


Benchmark  
Used

Components  
obtained  
*without* Pre-  
Alignment



Components  
obtained *with*  
Pre-  
Aligned  
Data



## Conclusions & Future Work

- Spectral distortion is an issue of great importance, and sensor de-calibration is currently dealt with in an open-loop manner.
  - The algorithm records every shift encountered, and can automatically indicate if a calibration is necessary.
- The flexibility of this approach is to be noted, as more types of spectral distortion can be considered.
  
- ALS assumes the number of components is known *a-priori*.
  - Extend spectral distortion robustness towards estimating it.
- Other component identification algorithms, such as ICA, are to be explored.